

KickC

Reference Manual

Version 0.7 (BETA)

by Jesper Gravgaard / Rex of Camelot

Contents

Contents	1
BETA	3
1 What is KickC?	4
The KickC Language	4
Optimized and Readable 6502 Assembler Code	4
Getting Started	6
2 KickC Language Reference	8
Variables	8
Data Types	8
Integers	8
Booleans	9
Pointers	9
Arrays	10
Constants	10
No Floating Point Types	10
Expressions	11
Arithmetic Operators	11
Bitwise Operators	11
Relational Operators	11
Logical Operators	12
Assignment Operators	12
Increment/decrement Operators	12
Pointer and Array Operators	13
Low/High Operators	14
Function Calls	14
Automatic Type Conversion and Type Casting	14
Operator Precedence and Parenthesis	15
Statements	16
Expressions and Assignmentst	16
If	17
While	17
Do-While	17
For	18
Break and Continue	18

Functions	19
Calling functions	19
Creating functions	19
The main() function	21
Comments	21
Importing code from other files	22
Variables Directives	22
Const	22
Register	23
Align	23
Volatile	23
Function Directives	23
Inline	23
Interrupt	24
Inline Assembler Code	25
Inline KickAssembler Code	27
Comparison with standard C	28
Supported	28
Not supported/implemented	28
Limitations / Modifications	29
Extensions	29
The KickC Libraries	29
3 Working with KickC	30
The Coding Workflow / Related Tools	30
Combining KickC and KickAssembler	30
Optimizing KickC Code	30
Handling Compiler Errors	30
4 The Compiler Architecture	30
Assembler Fragment Sub System	31

BETA

KickC is currently in beta, and crashes quite often resulting in cryptic errors. Also it will sometimes create ASM code that does not work properly. Feel free to test it and report any problems or errors you encounter, but do not expect it to produce production quality code. Also, be prepared that major breaking changes (to syntax, to semantics, etc.) may be implemented in the next versions.

1 What is KickC?

KickC is a compiler for a C-family language creating optimized and readable 6502 assembler code.

The KickC Language

The KickC language is classic C with some limitations, some modifications and some extensions to ensure an optimal fit for creating 6502 assembler code.

The language has the familiar C syntax and supports many of the basic features of C, so it should be quite easy to get started with if you have programmed in C or any similar language. Here is a simple “hello world” program, that prints “hello world!” at the top of the screen.

```
import "print"
void main() {
    print_str("hello world!");
}
```

The language has a number limitations compared to standard C, for example no support for structs, enums, unions or reentrant functions. Some features were omitted because they cannot be realized in a way that creates optimized 6502 assembler code. Others were omitted simply because they have not yet been implemented in the current version.

The language also have some modifications and extensions to standard C. The modifications and extensions were included either to allow creation of better 6502 assembler code or for convenience.

All limitations, modifications and extensions are described in the following sections.

Optimized and Readable 6502 Assembler Code

The KickC Compiler produces assembler code for the MOS Technology 6502 processor. The assembler code is produced as source code that can be assembled to binary by the Kick Assembler (<http://theweb.dk/KickAssembler>).

The compiler uses a number of modern optimization methods to create 6502 assembler code that executes as fast as possible and does not contain unnecessary boilerplate. The optimization techniques include

- Detection of constant values and expressions

- Optimized allocation of registers to variables
- Optimized parameter and return value passing to/from functions
- Minimizing the number of zero-page addresses used for storing variables
- Choosing optimal assembler instructions to represent each statement
- Removing unused functions, variables and code
- Peephole optimization of the generated assembler code

The optimization techniques are also explained in more detail in later sections.

Below a slightly more complex version of hello world, which prints “hello world!” with an added space between each letter on the first and third line of the C64 default screen at \$400. This example illustrates how the KickC compiler creates optimized readable 6502 assembler.

helloworld2.kc

```
byte* screen = $400;

void main() {
    byte* hello = "hello world!";
    print2(screen, hello);
    print2(screen+2*40, hello);
}

void print2(byte* at, byte* msg) {
    byte j=0;
    for(byte i=0; msg[i]!='@'; i++) {
        at[j] = msg[i];
        j += 2;
    }
}
```

helloworld2.asm

```
.label screen = $400
main: {
    lda #<screen
    sta print2.at
    lda #>screen
    sta print2.at+1
    jsr print2
    lda #<screen+2*$28
    sta print2.at
    lda #>screen+2*$28
    sta print2.at+1
    jsr print2
    rts
    hello: .text "hello world!@"
}
print2: {
    .label at = 2
    ldy #0
    ldx #0
    b1:
    lda main.hello,x
    sta (at),y
    iny
    iny
    inx
    lda main.hello,x
    cmp #'@'
    bne b1
    rts
}
```

The KickC compiler uses the following insights to optimize the helloworld2 program:

- The screen pointer is never modified and is therefore a constant location in memory.
- The second parameter to the *print2*-function (*msg*) always has the same value *main.hello*, so that can be hardcoded inside the method body instead of parsing it.

- The contents of *msg[i]* (ie. the hardcoded *main.hello* string) can be addressed using simple indexing.
- The *at*-parameter in *print2* is truly variable, so it is placed on zero-page (\$2 and \$3) and indirect indexing can be used for addressing the contents of *at[j]*.
- The X-register is optimal for the *i* variable in the *print2* function as it is good at indexing and incrementing.
- The Y-register is optimal for the *j* variable in the *print2* function as it is good at indirect indexing and incrementing.
- When 2 is added to the *j*-variable it is better to do INY twice than to use addition.
- The A-register is optimal for holding the current character *c* of the message being moved to the screen as LDA and STA can be efficiently indexed by X and indirect indexed by Y.

When generating Kick Assembler code the KickC compiler tries to ensure that the assembler code is readable and corresponds to the source C program as much as possible. This includes using the same names, using scopes and recreating constant calculations in assembler, when possible.

The KickC Compiler creates readable 6502 assembler code for the helloworld2 program by:

- Using the variable and function-names *screen*, *hello*, *main*, *print2*, *at* in the generated code
- Recreating the calculation of the constant *screen+2*40* in the assembler code as *screen+2*\$28*
- Creating a local named scope in the assembler-code for the methods *main* and *print2* by enclosing them in curly braces.
- Placing method-local data and labels inside the method scope. This allows other assembler code to access the local data/labels using dot-syntax eg. *main.hello* or *print2.at*

Getting Started

The KickC development is hosted on gitlab <https://gitlab.com/camelot/kickc>. Here it is possible to follow the development and to download the latest binary release.

You install KickC on your own computer by:

1. Download the newest KickC release zip-file from <https://gitlab.com/camelot/kickc/tags>
2. Unpack the zip-file to a folder of your own choice.

The zip-file contains the following

- o *lib* Folder containing the KickC JAR-file plus a few other JARs needed for running KickC (antlr4-runtime, picocli and KickAssembler).
- o *bin* Folder containing bat/sh-files for running KickC.
- o *stdlib* Folder containing KickC-files with useful library functions usable in your own program.
- o *examples* Folder containing some example KickC programs.

- This manual in PDF-format and some files with license-information.

KickC is written in Java. To use KickC you need to download and install a Java runtime from <https://www.java.com>. Java must be added to your PATH, or the environment variable JAVA_HOME must point to the folder containing the Java installation.

NOTE: KickC runs a lot faster on 64bit Java than on 32bit Java. You are therefore encouraged to ensure that your Java is a 64bit version. You can check by executing `java -version` in a Terminal/Command Prompt.

After installing KickC and you can compile a simple sample KickC program by doing the following:

MacOS

1. Start a Terminal
2. `cd` to the folder containing KickC
3. Enter the command
`bin/kickc.sh examples/helloworld/helloworld.kc`

Windows

1. Start a Command Prompt
2. `cd` to the folder containing KickC
3. Enter the command
`bin\kickc.bat examples\helloworld\helloworld.kc`

This compiles the helloworld KickC program `examples/helloworld/helloworld.kc` and produces assembler code in `examples/helloworld/helloworld.asm`. The resulting ASM-file can then be assembled using KickAssembler, producing a runnable program, that can be executed using an emulator or transfered to the real 8-bit hardware.

To make the workflow convenient KickC has a command line option (`-a`) to compile the resulting ASM code with KickAssembler. This is one of the reasons that the KickAssembler JAR is bundled with the release of KickC.

For even more convenience KickC also has a command line option (`-e`) that both assembles the ASM code and executes the resulting binary program in the VICE Commodore 64 emulator (<http://vice-emu.sourceforge.net/>). The option requires VICE x64 to be available in the PATH.

To compile, assemble and execute the example program `simple-multiplexer.kc` (a sprite multiplexer moving 32 balloons in a sinus on the screen) use the following command in the `kickc`-folder (assuming MacOS)

```
bin/kickc.sh -e examples/multiplexer/simple-multiplexer.kc
```


To create your own KickC-programs use any text-editor to create a source file containing a `void main()` function, save it to the file system (using the `.kc` extension is recommended) and compile it by passing it to `kickc.sh` (on MacOS) or `kickc.bat` (on Windows).

2 KickC Language Reference

KickC is a C-family language, and much of the syntax and semantics is the same as C99. In the following the different parts of the language is explained. Finally the differences between KickC and standard C are listed.

Variables

Variables are declared like in regular C by *type name* and can include an optional initialization assignment. The following declares a signed char variable with the name *size* and the initial value 12.

```
char size = 12;
```

If variables do not have an initial assignment they will be initialized with the default value zero.

It is possible to declare multiple variables with the same type by separating the names and optional initializations with commas. Here two unsigned int variables *a* and *b* are declared, *a* is initialized to 4 while *b* is initialized to the default value (zero).

```
unsigned int a = 4, b;
```

In KickC variables can be declared at any point in the program, outside functions or inside function declarations.

Data Types

Integers

KickC supports the standard C integer data types (`char`, `short`, `int`, `long`), but also adds some fixed size integer types, that have names more familiar on the 6502 platform (`byte`, `word`, `dword`).

Type Name	Description
byte unsigned byte	An unsigned 8 bit (1 byte) integer. Range is [0;255].

unsigned char	
signed byte char signed char	A signed 8 bit (1 byte) integer in two's complement. Range is [-128;127].
word unsigned word unsigned short unsigned int	An unsigned 16 bit (2 byte) integer Range is [0;65,535].
signed word short signed short int signed int	A signed 16 bit (2 byte) integer in two's complement. Range is [-32,767; +32,767].
dword unsigned dword unsigned long	An unsigned 32 bit (4 byte) integer. Range is [0, 4,294,967,295].
signed dword long signed long	A signed 32 bit (4 byte) integer in two's complement. Range is [-2,147,483,647, 2,147,483,647].

If the standard C integer types are declared without a unsigned/signed prefix they default to signed. If the special 6502-friendly integer types are declared without a unsigned/signed prefix they default to unsigned..

Integer literals can be either decimal, hexadecimal or binary. The syntax for hexadecimal integer literals support both C syntax (prefixing with 0x) and 6502 assembler syntax (prefixing with \$). Similarly the syntax for binary supports both prefixing with 0b and %.

Prefix	Format	Examples
	Decimal	12 53280
0x \$	Hexadecimal	0x40 \$dc01
0b %	Binary	0b101 %1100110011001100

Character literals are unsigned bytes / chars. The syntax for a character literal is the character enclosed in single quotes. Numerically the character is represented by the C64 screen code. The following initializes the variable *c* to the character 'c'.

```
byte c = 'c';
```

Booleans

KickC also has a boolean type called `bool`. The boolean literals are `true` and `false`. Underlying the boolean type is a byte containing either 0 (if `false`) or 1 (if `true`). The following is an example of a boolean variable called *enabled*.

```
bool enabled = true;
```

Pointers

Pointers to all integer types and booleans are supported and declared using the syntax `type*`. The following is an example, where *screen* is a pointer to a byte and *pos* is a pointer to a signed integer.

```
byte* screen;  
int* pos;
```

Pointers to pointers are also supported. Here an example of a pointer to a pointer to an unsigned char.

```
unsigned char** screenptr = &screen;
```

For functions it is only possible to use pointers to functions that has no return value and take no parameters.

Arrays

Arrays of integer and boolean types are supported using the syntax `type[]` or `type[size]`. For all practical purposes array variables are treated exactly like pointers.

Arrays can be initialized by an array literal written as comma-separated values inside curly braces eg. { 1, 2, 3 }. They can also be initialized with all zero values just by declaring the array to have a specific size.

String literals can also be used to initialize an array of unsigned bytes. The syntax for a string literal is the string enclosed in double quotes. Strings are per default zero terminated. It is possible to create a string that is not zero terminated by adding the special suffix `z` after the last double quote.

Arrays that are initialized will allocate the memory needed for the size.

In the following example, *sums* is array of 3 signed bytes initialized with zeros, *fibs* is an array of 6 signed integers containing the first fibonacci numbers. *msg* is an unsigned byte array

containing the numeric value of the 6 characters 'h', 'e', 'l', 'l' and 'o' plus a seventh value that is zero (because strings are zero terminated) while *msg2* only has the 6 characters without the final zero. Finally *bs* is simply a pointer to a boolean.

```
signed byte[3] sums;
int[] fibs = { 1, 1, 2, 3, 5, 8 };
byte[] msg = "hello";
byte[] msg2 = "hello"z;
bool[] bs;
```

Arrays of arrays are not supported.

Constants

Constants can be declared by using the `const` keyword.

```
const byte SIZE = 42;
```

The compiler is quite good at detecting constants automatically, so it is not strictly necessary to declare any constants. However declaring a constant can help make the code more readable and will generate an error if any code tries to modify the value.

When an array is declared constant only the pointer to the array is constant. The contents of the array can still be modified.

No Floating Point Types

KickC has no floating point types, as the 6502 processor has no instructions for handling these.

Expressions

Expressions in KickC consist of operands and operators. Operands are either data type literals or names of variables or constants. All well known expression operators from C and similar languages also exist in KickC. An example of an expression is `(bits & $80) != 0`

Arithmetic Operators

The arithmetic operators support performing simple numeric calculations

- `a + b` Addition
- `a - b` Subtraction
- `- a` Negation
- `+ a` Positive
- `a * b` Multiplication
- `a / b` Division

- `a % b` Modulo

Multiplication, division and remainder are allowed, however there is very limited run-time support for these operators as the 6502 has no instructions supporting them. Only multiplying and dividing by powers of 2 (eg 2, 4, 8, 16, ...) is supported at runtime since this is supported by bit shifting instructions. Multiplication and division can also be used for calculating values that end up being constant. If they are used in a way that requires runtime support beyond bit shifting the compiler will fail with an error.

For convenience plus (addition) can also be used for concatenating strings initializers with other strings or characters. The following initializes the variable *msg* with the text “hello world”.

```
byte[] msg = "hello" + ' ' + "world";
```

Bitwise Operators

The bitwise operators operate on the individual bits of the numeric operands.

- `a & b` Bitwise and
- `a | b` Bitwise or
- `a ^ b` Bitwise exclusive or
- `~ a` Bitwise not
- `a << n` Bitwise shift left n bits
- `a >> n` Bitwise shift right n bits

Relational Operators

The relational operators compare values and has a boolean value result.

- `a == b` Equal to
- `a != b` Not equal to
- `a < b` Less than
- `a <= b` Less than or equal to
- `a > b` Greater than
- `a >= b` Greater than or equal to

Logical Operators

The logical operators operate on boolean operands and has a boolean result.

- `a && b` Logical and
- `a || b` Logical or
- `! a` Logical not

When `&&` and `||` are used in *if*, *while*, *do-while* or similar statements they are short circuit-evaluated meaning that if *a* evaluates to *true* in `if(a || b) { ... }` then *b* is never evaluated. Similarly if *a* evaluates to *false* in `if(a && b) { ... }` then *b* is never evaluated.

Conditional Operator

The conditional operator is also called ternary operator because it is the only operator using three operands. It is used to choose between two different values.

- `a ? b : c` Conditional

It evaluates the first operand, which should be boolean. If the first operand evaluates to true it returns the value of the second operator. If the first operand evaluates to false it returns the value of the third operator. It uses short-circuit-evaluation meaning that only one of the two last operands are evaluated depending on the value of the first operand.

In this example `d` will be set to the value of `c` if `c` is positive and to `-c` if `c` is negative.

```
char d = c>0 ? c : -c;
```

Comma Operator

The comma operator can be used to evaluate multiple values in place of an expression. It evaluates the first operand and discards the results. Then it evaluates the second operand and returns the results.

- `a , b` Comma

Using it can produce code that is hard to read, however it can come to good use in `for()`-statements to increment multiple variables. Here an example of a `for()`-loop with two loop-variables `i` and `j`.

```
for(unsigned char i=0, j=0; i<32; i++, j+=2) { ... }
```

Assignment Operators

Assigning a value to a variable is also an expression operator that returns the value assigned. This means that assignments can be nested inside expressions, and that they can be chained if multiple variables should be assigned the same value like `a = b = 0`. An assignment of course has side effects, as it modifies the assigned variable.

Compound assignment operators, such as `a += b` is a convenient shorthand for updating the value of a variable. It works exactly like `a = a + b`.

- `a = b` Assignment
- `a += b` Addition assignment
- `a -= b` Subtract assignment

- `a *= b` Multiply assignment
- `a /= b` Divide assignment
- `a %= b` Modulo assignment
- `a <<=b` Left shift assignment
- `a >>=b` Right shift assignment
- `a &= b` Bitwise and assignment
- `a |= b` Bitwise or assignment
- `a ^= b` Bitwise exclusive or assignment

Increment/decrement Operators

The pre-increment/decrement and post-increment/decrement operators is a convenient way of incrementing/decrementing the value of a numeric variable just before or just after the value is used in an expression.

- `++a` Pre-increment
- `--a` Pre-decrement
- `a++` Post-increment
- `a--` Post-decrement

Pre-incrementing works just like incrementing the value of `c` before the statement, meaning that `a = b + ++c;` is the same as `c += 1; a = b + c;` Similarly post-incrementing works just like incrementing the value after the statement, meaning that `a = b + c--;` is the same as `a = b + c; c -= 1;`

Pointer and Array Operators

The two basic pointer operators are the `&a` address-of operator, which creates a pointer to `a` variable and the `*a` pointer dereference operator, which supports reading and writing the value pointed to by the pointer.

The array indexing operator `a[b]`, which supports reading and writing of array elements, is in fact also a pointer operator. Because an array variable is actually a pointer to the start of the array the array dereference operator `a[b]`, which is actually shorthand for `*(a+b)`.

- `&a` Address of
- `*a` Pointer dereference
- `a[b]` Array indexing

Low/High Operators

An extension in KickC is the inclusion of operators that allow addressing the low/high byte of a word, and the low/high words of a dword. These are well known from 6502 assemblers.

The low-operator <a addresses the low-byte of the word a, or the low-word if a is a dword. Similarly the high-operator >a addresses the high-byte of a word or high-word of a dword.

The low/high operator can also be used on the left side of assignments to modify only the low/high byte of a word or low/high word of a dword.

- <a Low part of
- >a High part of

The following example sets the low part of the word in a to 0. If a was \$0428 before the assignment it will be \$0400 afterwards.

```
<a = 0;
```

Function Calls

Function that returns a value can be called as part of an expression. Functions are called by the normal parenthesis-syntax with parameter values separated by commas. Coding functions is described in the section *Functions*.

- f(a,b) Function Call

Automatic Type Conversion and Type Casting

KickC handles automatic type conversions differently than standard C. Where standard C converts all small integers to int before evaluating expressions KickC supports evaluating operators for all types and only performs conversions if they are strictly necessary. Limiting the number of automatic type conversions helps creating better optimized 6502 assembler. In many cases KickC can even handle operators for two values of different type directly. For instance adding a byte to a word can be done in more optimal 6502 code than first converting the byte to a word and then adding the two words. In practice the difference to standard C rarely has any consequences.

Like standard C, KickC will ensure automatic type conversion (if necessary) as long as the type of one value can contain all values of the type of the other. For instance an unsigned byte can be automatically converted to a signed word as signed words can hold all possible unsigned byte values. An unsigned byte can not be automatically converted to a signed byte, since a signed byte cannot hold all possible byte values.

The automatic conversions that Kick can perform for each type are the following

Type	Can be automatically converted to
------	-----------------------------------

unsigned byte	unsigned word, signed word, unsigned dword, signed dword
signed byte	signed word, signed dword
unsigned word	unsigned dword, signed dword
signed word	signed dword
unsigned dword	-
signed dword	-

The cast operator can be used to perform explicit type conversion. Casting also allows conversions to a type that cannot hold all possible values, and where some information may be lost in the conversion, for example casting a signed byte to an unsigned byte.

- (type)a Casting

For sub-expressions containing only constants the KickC compiler tries to infer the type of the sub-expression. This is done by performing the calculation and then checking which types can hold the calculated value. For instance the calculation $4000/80$ is inferred to match any integer type except signed byte (since a signed byte cannot hold 128) . This also differs from standard C, where all constant integer numbers are ints unless specified otherwise.

Operator Precedence and Parenthesis

Operators precedence decides which operators are applied first when multiple operators are combined in an expression. For instance multiplication is performed before addition in $a*b+c$. In KickC operators generally have the same precedence as in standard C.

Precedence rules can be overridden by using explicit parentheses in expressions. For instance to perform addition before multiplication $(a+b)*c$.

- (a) Parenthesis

The following table shows KickC operator precedences. Operators at the top of the table binds most tightly.

Precedence	Operators	Associativity
1	a++ a-- f() a[b]	Left-to-right
2	++a --a +a ~a !a (t)a *a &a	Right-to-left

3	a*b a/b a%b	Left-to-right
4	a+b a-b	Left-to-right
5	a<<b a>>b	Left-to-right
6	<a >a	Left-to-right
7	a<b a<=b a>b a>=b	Left-to-right
8	a==b a!=b	Left-to-right
9	a&b	Left-to-right
10	a^b	Left-to-right
11	a b	Left-to-right
12	a&&b	Left-to-right
13	a b	Left-to-right
14	a?b:c	Right-to-left
15	a=b a+=b a-=b a*=b a/=b a%=b a<<=b a>>=b a&=b a^=b a =b	Right-to-left
16	a,b	Left-to-right

Statements

The statements of a KickC program control the flow of execution. KickC supports most statements supported by standard C.

Statements are separated by semicolons `stmt; stmt;` and can be grouped together in blocks using curly braces `{ stmt; stmt; }`.

Expressions and Assignments

All expressions are valid statements. There are two typical ways of using expressions as statements. The first is an assignment, which is an expression, modifying the value of a variable.

```
a += 2;
```

The second is calling a function that has a side effect.

```
print("hello");
```

If

The body of an if-statement is only executed if the condition is `true`. The if-statement can have an else-body, that is executed if the condition is not true.

The following if-statement prints "even" to the screen if `a` is even.

```
if((a&1)==0) { print("even"); }
```

The following if-statement increases `b` if `a` is less than 10 and decreases `b` otherwise.

```
if(a<10) { b++; } else { b--; }
```

While

The body of a while-loop is executed repeatedly as long as the condition is still true. The while-loop is executed by first evaluating the condition. If the condition is true the body is executed and the loop starts over. If the condition is not true execution continues after the loop. If the condition is not true the first time the loop is encountered then the body is never executed.

The following while-loop prints `i` dots on the screen, while counting `i` down to zero.

```
while(i!=0) { print("."); i--; }
```

Do-While

The do-while-loop is very similar to the while-loop. The body of a do-while-loop is executed repeatedly as long as the condition is true. In the do-while-loop the body is executed first and then the condition is evaluated. If the condition is true the loop starts over. If the condition is not true execution continues after the loop. The body of the loop is always executed at least once.

The following do-while-loop keeps scanning the keyboard until the space key is pressed.

```
do {  
    keyboard_event_scan();  
} while (keyboard_event_get()!=KEY_SPACE)
```

For

The for-loop is a convenient way of creating a loop, where a loop-variable is initialized, the body is executed, the loop-variable is incremented and finally the condition is evaluated to determine whether to repeat the loop again.

A for-loop has the following syntax

```
for(init; condition; increment) { body }
```

and is equivalent to the following KickC code

```
init;  
do {  
    body;  
    increment;  
} while(condition)
```

The body and increment is always executed at least once in a KickC for-loop. This differs from standard C, where the condition is evaluated before the body and increment, enabling for-loops where the body is never executed. The KickC behavior was chosen because it can create more efficient 6502 ASM code than the standard C behavior.

KickC has an additional convenience syntax for creating simple for-loops that loop over an integer range. The following for-loop executes the body 128 times with *i* having values 0,1,...,127

```
for(byte i : 0..127) { body }
```

And is equivalent to

```
for(byte i=0; i!=127+1; i++) { body }
```

This convenience syntax only accepts constants or expressions evaluating to constants as the ends of the integer interval. It can loop both backwards and forwards.

Break and Continue

The `break` statement terminates a loop, whereas `continue` statement forces the next iteration of a loop. These statements are very useful when creating complex loop logic.

The following loop prints a string on the screen, skipping all spaces by using the `continue` statement. When it encounters '@' in the string it stops printing using the `break` statement.

```
byte* screen = $400;  
byte[] str = "hello brave new world!@";  
for( byte i: 0..255) {  
    if(str[i]=='@') break;  
    if(str[i]==' ') continue;  
    *screen++ = str[i];  
}
```

```
}
```

Functions

Functions are named pieces of code that can be reused by calling them and passing different parameters.

Calling functions

In the following code a function called `max` is called 3 times. The `max`-function takes 2 byte parameters and returns the maximal value of the two. After this code `m` will have the value 31 and `n` will have the value 47.

```
byte m = max(31, 9 );  
byte n = max(m, max(47, 7));
```

In general a function is called using the syntax:

```
name(param1, param2, ...)
```

Where

- *name* is the name of the function
- *param1* is the value of the first parameter
- *param2* is the value of the second parameter

The number of parameters passed must exactly match the number of parameters the function expects.

If the function returns a value then the function call can be used as part of any expression. An example of this can be seen in the nested call to `max` above.

Creating functions

Functions are created by adding function declarations to your program. The following is a declaration of the `max`-function used above. It expects two byte value parameters, finds the largest one and returns it.

```
byte max(byte a, byte b) {  
    if(a>b) {  
        return a;  
    } else {  
        return b;  
    }  
}
```

```
}
```

In general a function declaration has the following syntax:

```
return-type name(param-type1 param-name1, param-type1 param-name1, ...) { body }
```

Where

- *return-type* is the type of value that the function returns
- *name* is the name of the function
- *param-type1* is the type of the first parameter
- *param-name1* is the name of the first parameter
- *param-type2* is the type of the second parameter
- *param-name2* is the name of the second parameter
- *body* is the code performing the task of the function

If a function does not return a value it must declare the return type as `void`.

The parameter declaration inside the parenthesis describes how many parameters must be passed when calling the function, the types of the parameters to be passed and names the parameters have inside the functions body code. The `max-function` above takes 2 byte parameters, named `a` and `b`.

The function body is the code executed when calling the function. In the body code the declared parameters can be used as variables and will have the values passed by the call.

The special statement `return` is used to return a value to the caller. The `return` statement exits the function immediately.

The following statement exits the function and returns the sum of values `a` and `b`.

```
return a+b;
```

The `main()` function

All KickC programs must have exactly one function called `main`. The `main` function is the starting point of the program. In KickC the `main()` function takes no parameters and returns no value.

The following is a very simple KickC program with a `main` function that turns the screen background color black and exits.

```
import "c64"
```

```
void main() {
    *BGCOL = BLACK;
}
```

When compiling the main-function generates a C64 BASIC program containing a single SYS command which starts the execution of the compiled KickC program.

The following is the KickAssembler code resulting from compiling the KickC program above. BasicUpstart is KickAssemblers way of creating a BASIC-program with a single SYS command.

```
.pc = $801 "Basic"
:BasicUpstart(main)
.pc = $80d "Program"
    .label BGCOL = $d021
    .const BLACK = 0
main: {
    lda #BLACK
    sta BGCOL
    rts
}
```

Comments

Two types of comments are supported in KickC. Anything inside a comment has no effect on the generated code.

Block comments, started with `/*` and ended with `*/` can span multiple lines. They can sometimes be useful for commenting out large parts of programs.

```
/* A multi-line
block comment */
```

Single line comments are started with double-slash `//` and ends at the next newline

```
// a single-line comment
```

Importing code from other files

KickC differs from standard C in the way programs are split into multiple files. In KickC you do not need to split your code into header and code files. Instead you can simply use the `import` keyword to import another KickC source file. The compiler will do the work needed to keep track of which files import each other and ensure that the content of all imported files is compiled once.

The following imports the `keyboard.kc` file, that is part of the KickC standard library. The `keyboard.kc` file has functions for reading the C64 keyboard.

```
import "keyboard"
```

It is optional whether you include the KickC source extension `.kc` in your import statements. The compiler automatically adds `.kc` to any import if the import statement does not have the extension.

When importing files the compiler first searches through the current folder where the file that has the `import` statement is located, then it searches each library folder added by the `-libdir` option to the compiler command.

Imports can be told to look in subfolders by prefixing the filename with a slash-separated path. Here is an example where graphics code files are located in a subfolder:

```
import "graphics/character"
```

Variables Directives

KickC has a number of directives can be used for controlling how a variable works. Variable directives are can be added before or after the type of the variable.

Const

The `const` directive is used to declare a constant. The declaration must also contain an assignment and the compiler will issue an error if the variable is assigned anywhere else.

```
const byte SPRITES = 8;
```

Register

The `register` directive is used to instruct the compiler to use a specific CPU register for the variable. The compiler is quite good at optimizing register usage, so using this directive will often produce slower code than letting the compiler do the optimization itself. Using this directive can cause the compiler to fail if it is impossible to compile the program with the variable assigned to the register.

```
byte register(X) i;
```


Align

The `align` directive is used to control the placement of arrays and strings in memory. For instance `align($40)` will ensure that the memory address where the data is placed is a multiple of \$40 bytes. This can be useful when trying to optimize the performance of your program.

```
byte[$100] align($100) sine;
```

Volatile

The `volatile` directive tells the compiler that the value of the variable might change at any time. The `volatile` keyword must be used for variables that are shared between code running “simultaneously”. An example is when coding with interrupts (see the `interrupt` directive). The directive prevent the compiler from using all optimizations, where it assumes it can guess the value of the variable from the surrounding code. It will also ensure that the compiler does not produce code where the value of the variable is held in a register.

```
volatile byte sprite_ypos;
```

Function Directives

KickC also has a few directives that instruct the compiler to treat functions in a specific way.

Inline

The `inline` function directive instructs the compiler to inline the whole function body everywhere the function is called. This can be used for optimizing your code since it allows the compiler to optimize the code of each function call independently, for instance by identifying constants in each call. It also saves the CPU cycles normally needed to call the function and return from it. The trade-off is that your program will compile into more bytes of code.

```
inline byte sum( byte a, byte b) {  
    return a+b;  
}
```

Interrupt

The `interrupt` function directive is used for creating interrupt handler functions.

```
interrupt(kernel_keyboard) void irq() {  
    *BGCOL = WHITE;  
    *BGCOL = BLACK;  
}
```

Setting up an interrupt on the C64 is done by assigning a pointer to an interrupt handler function to one of the interrupt vectors placed at specific addresses in the memory. Below is an example of setting up the kernel IRQ vector (at \$314 in memory) to run the `irq()` function declared above. When setting up interrupts it is good practice to surround the code with the SEI/CLI instructions to prevent any interrupt from occurring during the setup itself.

```
import "c64"

void main() {
    asm { sei }
    *KERNEL_IRQ = &irq;
    asm { cli }
}
```

Inside the parentheses of the interrupt directive the type of interrupt handler function is specified. This controls what kind of code is generated for saving/restoring register values and how the interrupt is exited:

- `kernel_keyboard` Interrupt served by the kernel called through \$0314-5. Will exit through the kernel using \$ea31, which runs the normal kernel service routine that includes checking and handling keyboard input.
- `kernel_min` Interrupt served by the kernel called through \$0314-5. Will exit through the kernel using \$ea81, which restores the registers and exits.
- `hardware_all` Interrupt served directly from hardware through \$ffffe-f or \$ffffa-b. Will exit through RTI and will save/restore ALL registers
- `hardware_clobber` Interrupt served directly from hardware through \$ffffe-f or \$ffffa-b. Will exit through RTI and will save necessary registers based on a clobber analysis of the interrupt handler code.
- `hardware_none` Interrupt served directly from hardware through \$ffffe-f or \$ffffa-b. Will exit through RTI and will save/restore NO registers.

If your interrupt code needs to utilize global variables to communicate with other parts of the program or to store state between interrupt calls these variables should be declared as `volatile`.

Inline Assembler Code

Programs can include inline assembler code inside a function body. This can for instance be useful for interfacing to machine code such as the BASIC/KERNAL or for modifying processor flags (such as the interrupt flag or decimal flag).

Inline assembler is created using the `asm` statement with a body containing the assembler code. The following is an example setting the processor interrupt flag.

```
asm {
    sei
}
```

The assembler language usable within the curly braces is pretty limited standard syntax 6502 assembler using the same syntax as KickAssembler (and most classical 6502 assemblers). The following is supported:

- All normal 6502/6510 instructions and addressing modes
 - Immediate lda #%10101010
 - Absolute eor 1024
 - Zeropage rol 2
 - Relative bne nxt
 - Absolute indexed X adc \$2000,x
 - Absolute indexed Y cmp sintab,y
 - Zeropage indexed X sbc 2,x
 - Zeropage indexed Y stx \$fe,y
 - Zeropage indexed indirect X lda (\$20,x)
 - Zeropage indirect indexed Y ora (14),y
 - Indirect jmp (\$1000)
 - Implied (no operand) tax
- Labels
 - Normal labels next:
 - Multi labels next!:
- Data
 - Bytes .byte \$10, \$20

The parameters for instructions and the data bytes can be written as expressions supporting

- Literal numbers in decimal, binary or hexadecimal using the same syntax as KickC literal numbers eg. 1024, \$3fff, %10101010
- Literal characters eg. 'q'
- Constant variables declared in the C-code eg. SCREEN
- Labels declared within the assembler code
- Math operators + - * / < > << >>
- Parenthesis using [and] to avoid the assembler interpreting them as indirect addressing mode.

The ability to reference constant variables declared outside the assembler code allows the inline assembler to interact with data in the C-part of the program. The following is an example referencing the constant variable SCREEN.

```
const byte* SCREEN = $400;
```

```

void main() {
    asm {
        lda #'c'
        sta SCREEN+40
    }
}

```

There is also support for referencing labels declared inside inline ASM in other functions using the special `.` operator (eg. `clearscreen.fillchar`). This makes it possible for ASM in one function to modify the code of ASM inside other scopes.

The KickC compiler understands the inline assembler code and attempts to optimize it during the compilation process. For instance it can analyze which registers are clobbered by the inline assembler, and optimize surrounding KickC-code register usage.

If your inline ASM contains a JSR call the compiler assumes that all registers are clobbered. However, it is possible to add a `clobbers` directive in parenthesis specifying exactly which registers are clobbered by your inline assembler code. Here is an example of inline assembler where the directive is used to specify that the JSR only clobbers the A- and X-registers.

```

void playMusic() {
    asm(clobbers "AX") {
        jsr $1000
    }
}

```

Since the compiler understands the inline assembler it will also modify the assembler code if this leads to faster execution, for instance removing an immediate load-instruction that loads a value that the register is already guaranteed to contain.

Inline KickAssembler Code

The inline assembler code described above can be very useful, but only supports very rudimentary assembler features. The limitations allow the compiler to understand the assembler code and include it in optimizations.

If you need advanced assembler features in your code such as macros, loops or importing binary files or images it is possible to include inline KickAssembler code in your KickC program using the `kickasm` statement. The body of the `kickasm` statement must be enclosed in double curly braces and is passed directly to KickAssembler. The KickC compiler does not make any attempt to parse or understand the KickAssembler code. All advanced KickAssembler features are described in the manual here <http://theweb.dk/KickAssembler>.

The following is an example of inline KickAssembler code creating assembler for really fast screen clearing (1000 STA operations with no looping).

```
void clearscreen() {
    kickasm(uses screen) {{
        lda #0
        .for (var i = 0; i < 1000; i++) {
            sta screen+i
        }
    }}
}
```

Inline KickAssembler can reference constant variables declared in the surrounding C-code. To ensure that the KickC compiler knows that the inline KickAssembler uses a constant you should add a uses directive in parenthesis. This will ensure that KickC knows that the symbol is used, and for instance prevent the compiler from removing the symbol entirely if it is not used anywhere else.

Inline KickAssembler is also allowed outside function bodies. Here it allows utilizing KickAssemblers powerful macro language to initialize data tables. To specify where the resulting data bytes ends up in memory the pc directive is specified in parenthesis. Here an example of generating a table with sinus values.

```
const byte* sintab = $1000;
kickasm(pc sintab) {{
    .fill $100, 127.5 + 127.5*sin(toRadians(i*360/256))
}}
```

It is also possible to use inline KickAssembler for loading pictures, music or other binary files and generating data bytes from these. When loading binary files in the inline KickAssembler code it is necessary to inform the KickC compiler using a resource directive within parenthesis. This is needed because KickC may have to copy the used resource files to the output directory where the compiled assembler code is written. Here an example of including a sprite from a PNG image file.

```
const byte* SPRITE = $0c00;
kickasm(pc SPRITE, resource "balloon.png") {{
    .var pic = LoadPicture("balloon.png", List().add($000000, $ffffff))
    .for (var y=0; y<21; y++)
        .for (var x=0;x<3; x++)
            .byte pic.getSinglecolorByte(x,y)
}}
```

Comparison with standard C

Not supported/implemented

- Floating point types *float, double*
- Runtime multiplication *a * b*
- Runtime division *a / b*
- Runtime modulo *a % b*
- Enum *enum Status { on, off } status;*
- Struct *struct Point { byte x; byte y; } p;*
- Union *union { byte b; word w; } u;*
- Array of arrays *byte[4][4] baa;*
- Function pointers w. param *void(byte)*;*
- Function pointers w. return *byte()*;*
- Heap Allocation *dword* dw = malloc(4);*
- Recursive functions *byte fib(byte n) { return fib(n-1)+fib(n-2); }*
- Sizeof operator *byte s = sizeof (word);*
- Alignof operator *byte s = alignof (word);*
- Variadic functions *printf(const byte* format, ...)*
- C preprocessor (see imports)
- C standard library

Limitations / Modifications

- For-loops always execute the body at least once.
- Multiplication and division only supported for constants (no runtime support for multiplication/division without using a library and a function call.)
- Arrays and strings are always statically allocated (as data bytes in the resulting assembler).
- Conditions in *if*, *while*, *do-while* and similar statements only accept boolean values. Numeric values are not accepted without casting.
- Alignment directive *align(\$100)*
- Register directive *register(X)*
- Inline assembler *asm { SEI CLD };*
- Main-function *void main() { ... }*

Extensions

- 6502 types *byte, word, dword*
- Imports *import "print"*
- Forward referencing variables in the outer scope

- Ranged for-loops *for(byte i: 0.. 10) {}*
- Word operator *word w = { hi, lo };*
- Lo/hi-byte operator *byte lo = <w; <w = 12;*

The KickC Libraries

No runtime library!

Some libraries

- print
- c64
- c64dtv
- keyboard
- division
- Multiply
- Fast multiply
- sinus
- Basic-floats

3 Working with KickC

KickC Command Line Reference

The Coding Workflow / Related Tools

- Assembling
- Executing (Emulators or The Real Thing)
- Editing
- Reporting Issues
- The Source Code
- Contributing

Combining KickC and KickAssembler

Optimizing KickC Code

- Use `do {} while()` instead of `while() {}`
- Unsigned types are more optimal than signed types.
- Use array indexing instead of incrementing pointers.
- Booleans are not always very efficient. Often bytes are better.

- Use inline functions
- Use (experimental) inline loops
- Use normal assembler optimization techniques (putting a calculated result that is used multiple times into a variable instead of repeating the calculation, create arrays for lookup instead of repeating a calculation many times, loop unrolling,)

Handling Compiler Errors

Missing Assembler Fragments

4 The Compiler Architecture

1. Loading and Parsing
2. Creating The Single-Static Assignment Control Flow Graph and Symbol Table
3. Optimizing the SSA Control Flow Graph
4. Control Flow Graph Analysis
5. Register Allocation
6. Assembler Code Generation using Assembler Fragments
7. Assembler Code Optimization

Assembler Fragment Sub System

Adding missing assembler fragments

The format for the values in the fragment name is:

1. "v" value / "p" pointer
2. "b" byte / "w" word / "d" dword
3. "u" unsigned / "s" signed / "o" boolean
4. "aa" A-register / "xx" X-register / "yy" Y-register / "z1" zeropage {z1} / "c1" constant {c1}.

When {c1} is used for values it is an immediate value, eg. in vbuc1, {c1} is a constant unsigned byte value.

When c1 is used for pointers it is an address in main memory, eg. in pbsc1, {c1} is a constant pointer to a signed byte. This means that {c1} is effectively an address in main memory.

vwuz1_gt_vbsc1_then_la1 for example means [if] variable word unsigned zero-page value {z1} is greater than variable byte signed constant {c1} then [goto] label {la1}.

Fragments can use \$ff as temporary storage (and \$fe if 2 addresses are needed).

Before adding the fragment try compiling with the `-vfragment` flag. It will show you all the different fragments that the compiler is considering. You only need to implement one and then the fragment synthesizer can create what it needs from that.

If you are wondering how a specific fragment looks you can ask the compiler using the `-fragment` flag. The following command will show all the different variations of assembler the compiler can use when needing to assign an unsigned byte in a zeropage variable `{z1}` to the value found in a table of unsigned bytes `{c1}` indexed by another unsigned byte variable on zeropage `{z2}`.

```
kickc.sh -fragment vbuz1=pbuc1_derefidx_vbuz2
```

You do not need to restore any register values in fragments. In fact that is part of the optimizers strength.

The compiler analyses the ASM in each fragment and determines which registers are clobbered. When allocating variables to registers it avoids any allocation where a fragment clobbers a register holding a variable value that is needed later in the code. So it will avoid holding a value in A that is needed after any fragment that clobbers A - and will instead look at different options (X, Y or on zeropage).

This produces much better ASM than each fragment restoring register values since it allows the compiler flexibility in choosing the register/zeropage allocation that minimises the number of cycles the code consumes.

This is further improved by the compiler treating each assignment to a variable as a separate variable - meaning it often ends up choosing to hold much used variables in different registers or on zero page for different parts of the code.